# How EnKF can benefit from or contribute to 4D-Var (an EnKF perspective)

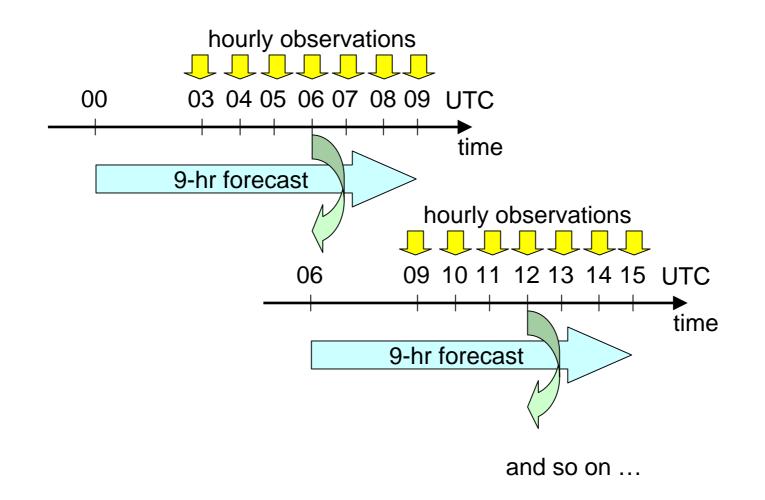
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# Outline

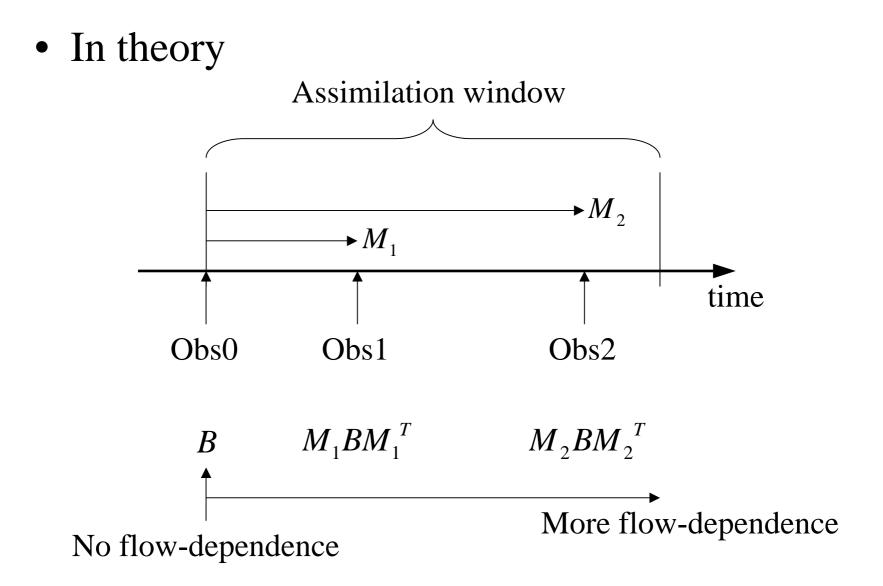
- JMA's experience on...
  - 4D-Var with flow-dependent background error variance
    - Miyoshi and Kadowaki (2008, SOLA)
  - EnKF development
    - Miyoshi, Sato, and Kadowaki

- Synergies in an EnKF perspective:
  - The comparison helps the EnKF development
    - To identify errors
    - To come up with ideas to simulate VarBC

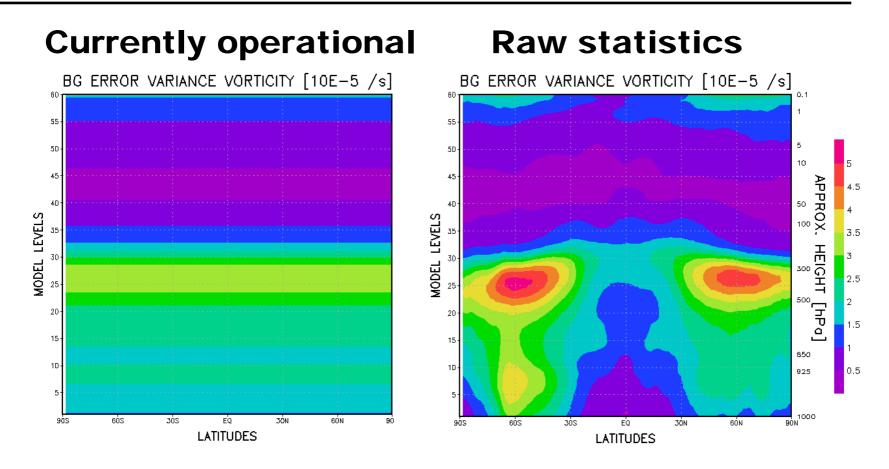
### JMA's forecast-analysis cycle



## Flow-dependence in 4D-Var



## B in JMA 4D-Var



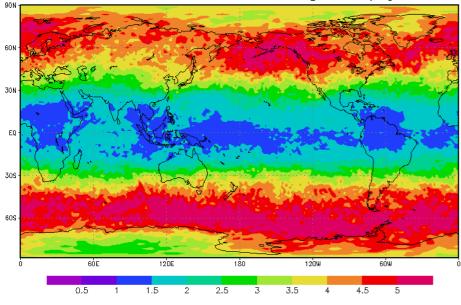
The operational system assumes horizontal homogeneity.

## Flow-dependent B estimate

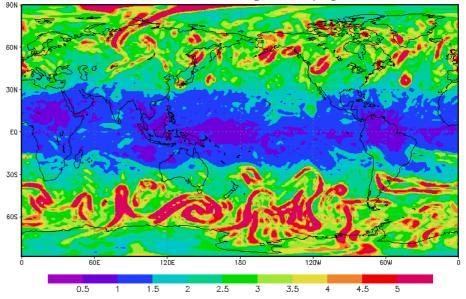
#### 1-year average

#### Snapshot

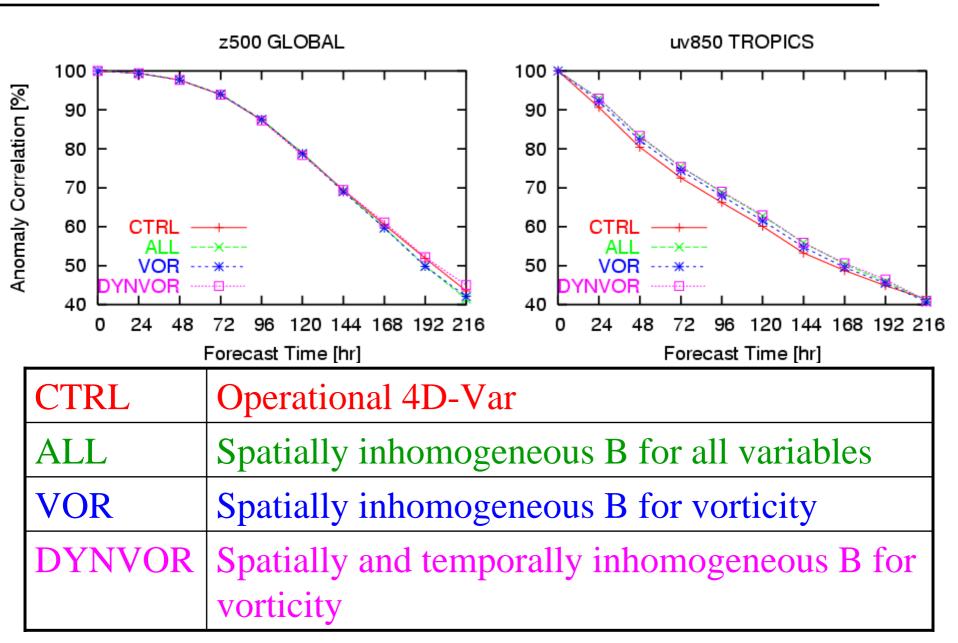
BG ERROR VARIANCE VORTICITY [10E-5 /s]



BG ERROR VARIANCE VORTICITY [10E-5 /s] 00Z18AUG2006



# Impact of B in 4D-Var



# Flow-dependent B in 4D-Var

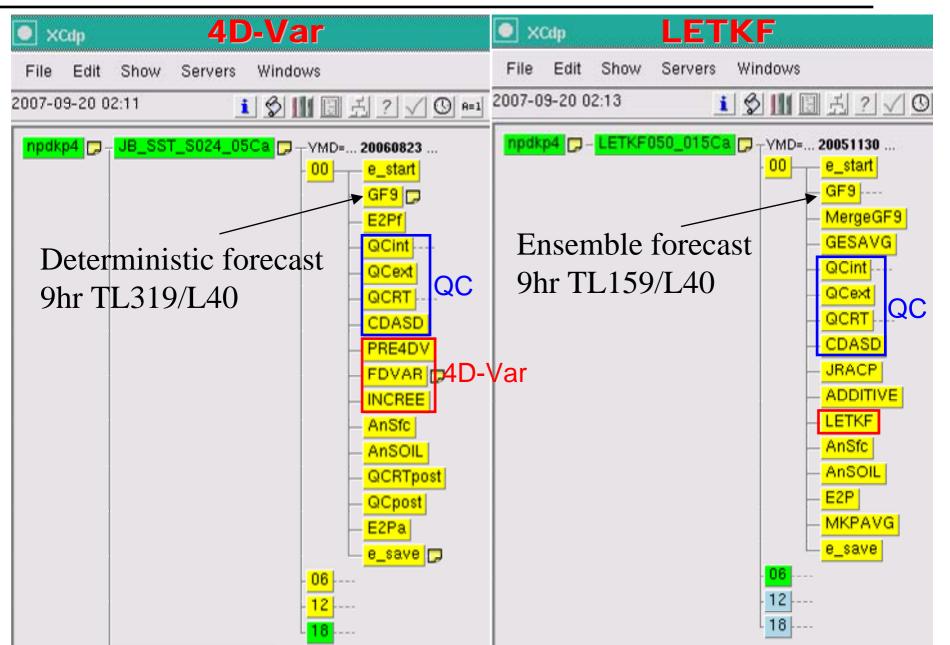
- 4D-Var shows weak sensitivity to the choice of B (variance)
- EnKF could provide flow-dependent B to improve 4D-Var

## Development of EnKF – JMA's experience

• Local ensemble transform Kalman filter (LETKF, Hunt et al. 2007; Ott et al. 2004) has been applied to JMA global spectral model (GSM)

• Embedded into the quasi-operational experimental system (NAPEX by K. Onogi)

## Quasi-operational Experimental System



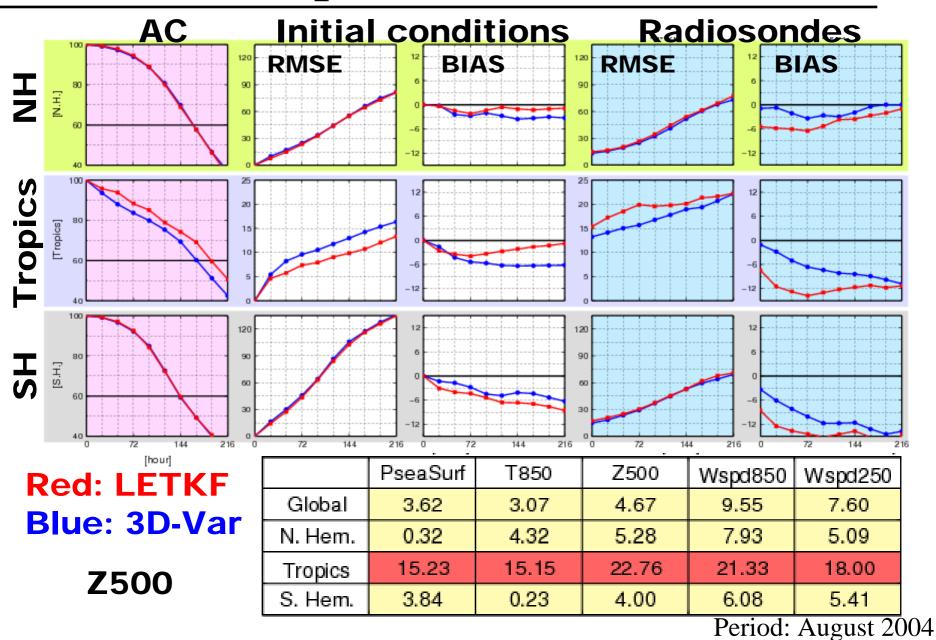
# Computational time

LETKF	4D-Var	
11 min x 60 nodes	13 min x 60 nodes	
5 min for LETKF	(Operations)	
6 min for 9-hr ensemble forecasts		
TL319/L60/M50	Inner: T159/L60	
(estimated)	Outer: TL959/L60	

6 min (measured) x 8 nodes for LETKF with TL159/L40/M50

At first LETKF was slower than 4D-Var, but now it's faster after improvement. <u>4D-Var was a benchmark to improve EnKF!</u>

## Overall comparison with 3D-Var



# Overall comparison with 4D-Var

	PseaSurf	T850	Z500	Wspd850	Wspd250
Global	-9.00	-10.45	_10.64	2.38	0.13
N. Hem.	-4.47	-2.95	-1.72	3.74	0.66
Tropics	0.48	-11.66	_17.60	11.69	9.88
S. Hem.	-10.90	-14.51	-13.00	-1.52	-3.81

Apply adaptive bias correction

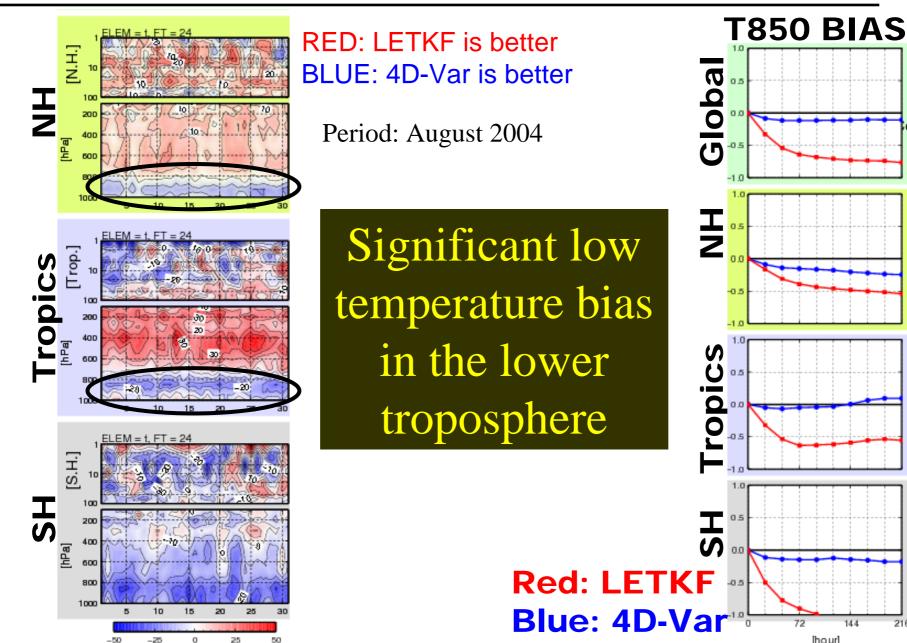
	PseaSurf	T850	Z500	Wspd850	Wspd250
Global	_6.19	-4.36	-5.71	3.66	1.32
N. Hem.	-4.18	1.12	0.91	3.98	0.57
Tropics	6.86	3.39	3.09	14.07	10.21
S. Hem.	-7.60	-8.91	-7.91	-0.08	-1.62

#### Some bugs fixed in surface emissivity calculation

	PseaSurf	T850	Z500	Wspd850	Wspd250
Global	-5.21	-2.33	-4.21	3.94	1.73
N. Hem.	-3.89	2.06	1.32	4.30	1.30
Tropics	7.05	6.49	7.44	13.58	9.57
S. Hem.	-6.35	-6.47	-6.20	0.39	-1.14

Period: August 2004

# Cold bias was identified



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## Satellite radiance bias correction

Observation y has a bias b

 $b = b^{scan} + b^{air}$ Air mass bias (dependent on atmospheric state) Scan bias (constant) Statistically estimated offline

Coefficients  $\beta$  of predictors p are estimated statistically

$$p^{air} = p^T \beta$$

$$\begin{bmatrix} 2 \text{enith angle} \\ \text{Surface temperature} \\ \text{Constant} \\ \text{etc.} \end{bmatrix}$$

# Adaptive bias correction

Coefficients would change partly due to the deterioration of sensors

Allow temporal variation of the coefficients using data assimilation

Variational bias correction (e.g., Dee 2003; Sato 2007)

$$J(x) = \frac{1}{2}(x - x^{f})B^{-1}(x - x^{f})^{T} + \frac{1}{2}(y - Hx^{f})R^{-1}(y - Hx^{f})^{T}$$

 $J(x,\beta) = \frac{1}{2}(x-x^{f})B^{-1}(x-x^{f})^{T} + \frac{1}{2}(\beta-\beta^{f})B_{\beta}^{-1}(\beta-\beta^{f})^{T}$ 

 $+\frac{1}{2}(y - p^T \beta - Hx^f)R^{-1}(y - p^T \beta - Hx^f)^T$ 

Find the minimizer  $\beta$  of the cost function J through the variational procedure

### Adaptive bias correction with LETKF

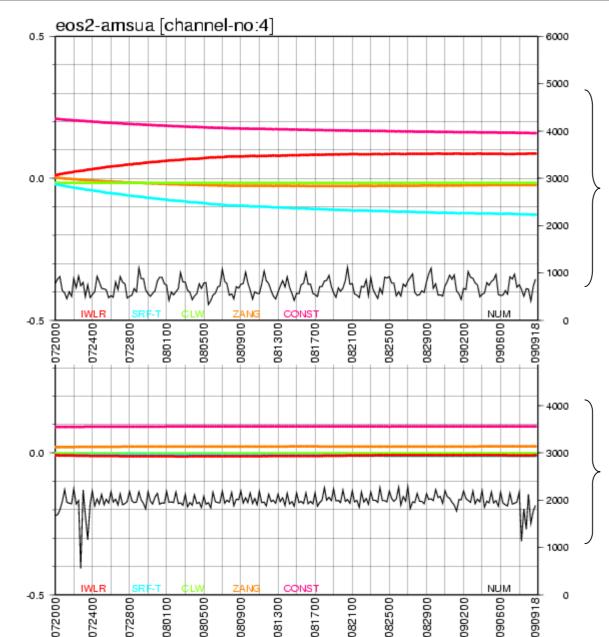
Analytical solution of the variational problem: minimizer (x,  $\beta$ )  $\begin{cases} \delta x = (B_x^{-1} + H^T R^{-1} H)^{-1} H^T R^{-1} (d - p^T \delta \beta) \\ \delta \beta = (B_\beta^{-1} + p R^{-1} p^T)^{-1} p R^{-1} (d - H \delta x) \end{cases}$ 

Adaptive bias correction with LETKF

1. Solve the LETKF data assimilation problem first  $\delta x = B_x H^T (HB_x H^T + R)^{-1} d = (B_x^{-1} + H^T R^{-1} H)^{-1} H^T R^{-1} d$   $-p^T \delta \beta \text{ difference}$ 

2. Solve the equation for  $\beta$  explicitly  $\delta\beta = (B_{\beta}^{-1} + pR^{-1}p^{T})^{-1}pR^{-1}(d - H\delta x)$ This coincides with the variational BC

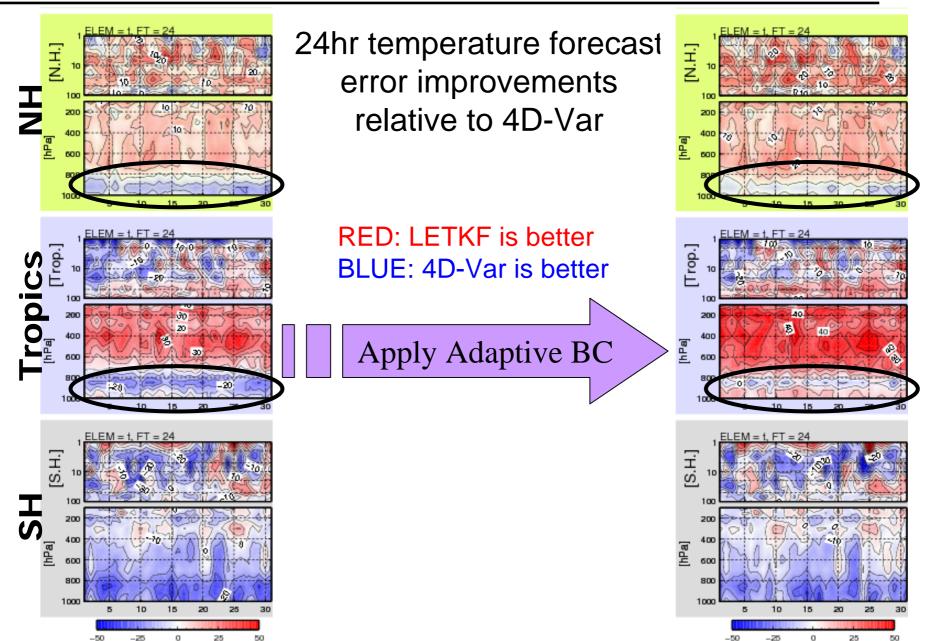
## Time series of bias coefficients



AMSU-A 4ch (sensitive to middle-lower troposphere) indicates significant drift from those estimated by 4D-Var

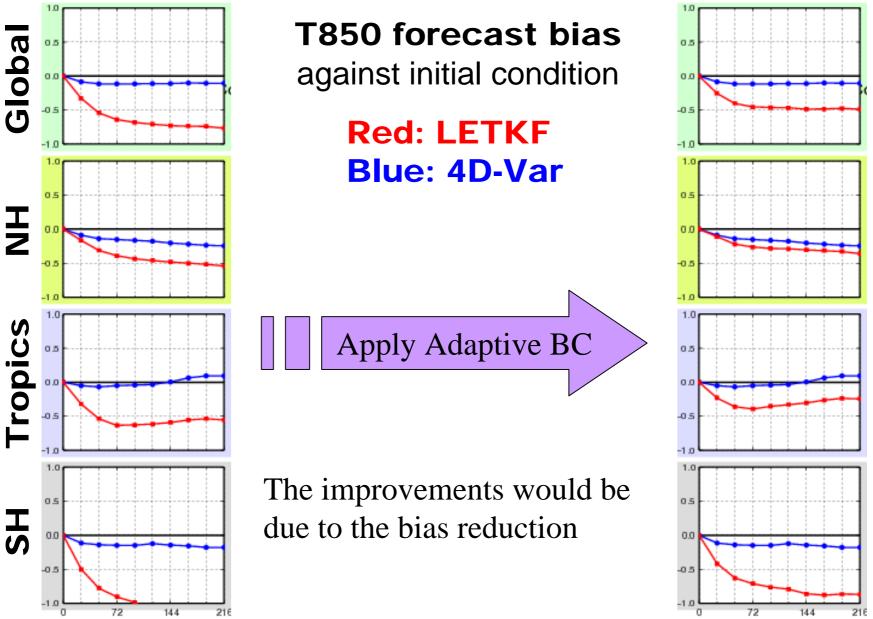
AMSU-A 6ch (sensitive to upper troposhere) and other sensors/channels indicate no significant drift

# Impact by adaptive bias correction



# Bias reduction

[hour]



lhourl

## Reason for bias drifts in AMSU-A 4ch

FACTS:

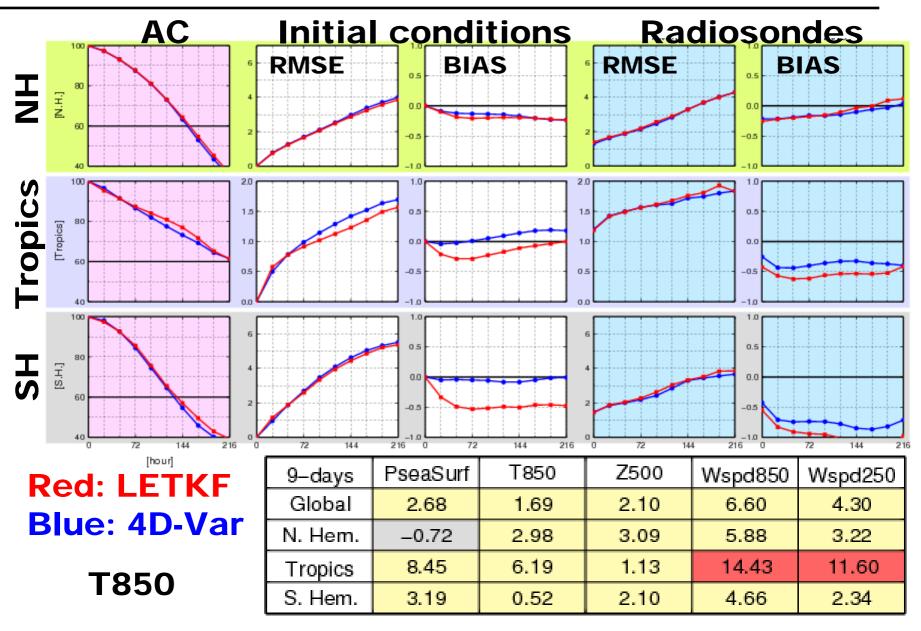
- ✓ 4D-Var uses RTTOV-7
- ✓ LETKF uses RTTOV-8

✓ AMSU-A ch.4 is sensitive to surface emissivity and lower tropospheric temperature

✓ A known bug in the surface emissivity model "FASTEM-2" in RTTOV-7, where the surface emissivity is spuriously overestimated

- 4D-Var VarBC corrects the "spurious" bias caused by the bug
- Therefore, observed radiances (bias corrected) are too large for LETKF
- Thus, the lower troposphere is heated by assimilating the too large radiance observations, which explains the cold forecast bias relative to analysis (because analysis is too warm)
- The adaptive BC within LETKF corrects the wrong bias

#### Experiments without satellite radiances



## Future work

- Improve the use of satellite radiances
  - QC system with RTTOV-8
    - 4D-Var began to use RTTOV-8 since Oct 15, 2008
  - Applying a better localization method

- Test with a different model
  - It is known that JMA model has a significant bias

# Conclusion

#### Synergistic development

- We learned from the comparison with 4D-Var to identify problems in EnKF
  - We could easily find the cold forecast bias in EnKF
- Overcome inferior points
  - Computational time: tuned to be faster than 4D-Var
  - Adaptive bias correction to simulate VarBC
  - Covariance localization for temporally/spatially integrated observations

Finding superior/inferior points through inter-comparison is important and beneficial for both 4D-Var and EnKF.



# Recent improvements

• Assimilation of satellite radiances

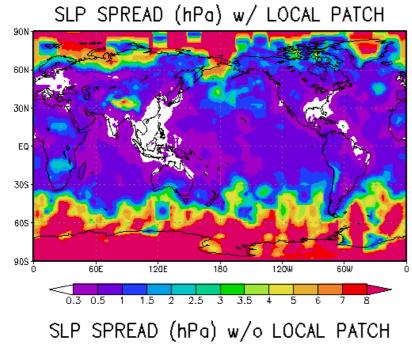
 greatly improves the analysis accuracy Miyoshi and Sato, 2007: SOLA, 37-40.

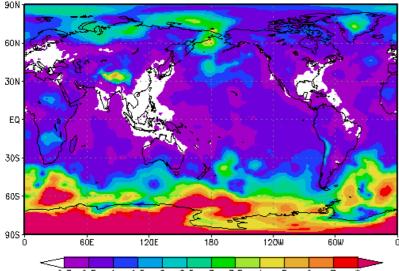
• Removing local patches

 solves the discontinuity problem near the Poles Miyoshi et al., 2007: SOLA, 89-92.

- Efficient MPI parallel implementation
  - solves the load imbalance problem
  - accelerates by a factor of 3 about 30% faster than operational 4D-Var with similar settings
- Adaptive satellite bias correction
  - a new idea analogous to the variational bias correction
  - showing great positive impact

# LETKF without local patches





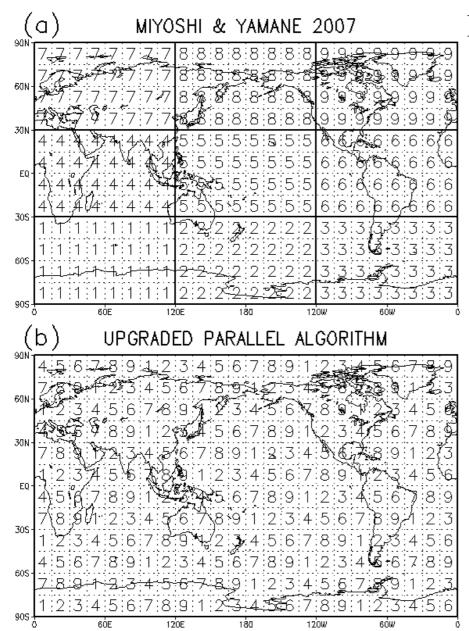
SLP analysis ensemble spread after the first analysis step

The discontinuities caused by the local patches disappear.



Miyoshi et al. 2007

# Efficient parallel implementation

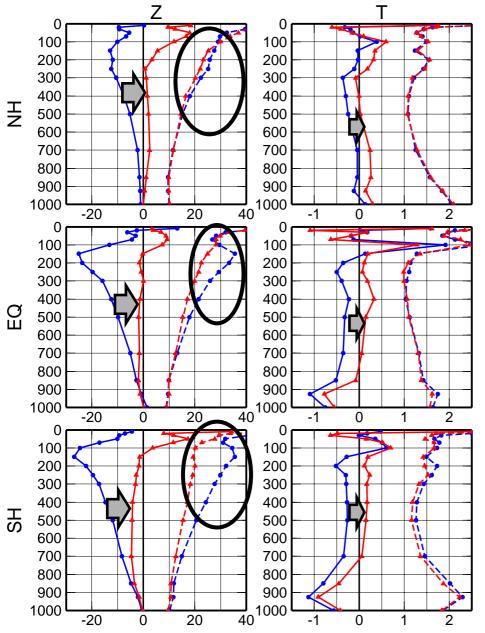


In the case of 9 comp. nodes

Irregular observing network causes significant load imbalances

Revising the node separation, we solved the load-imbalance problem almost completely; ~3 times faster computation

# Impact by satellite radiances

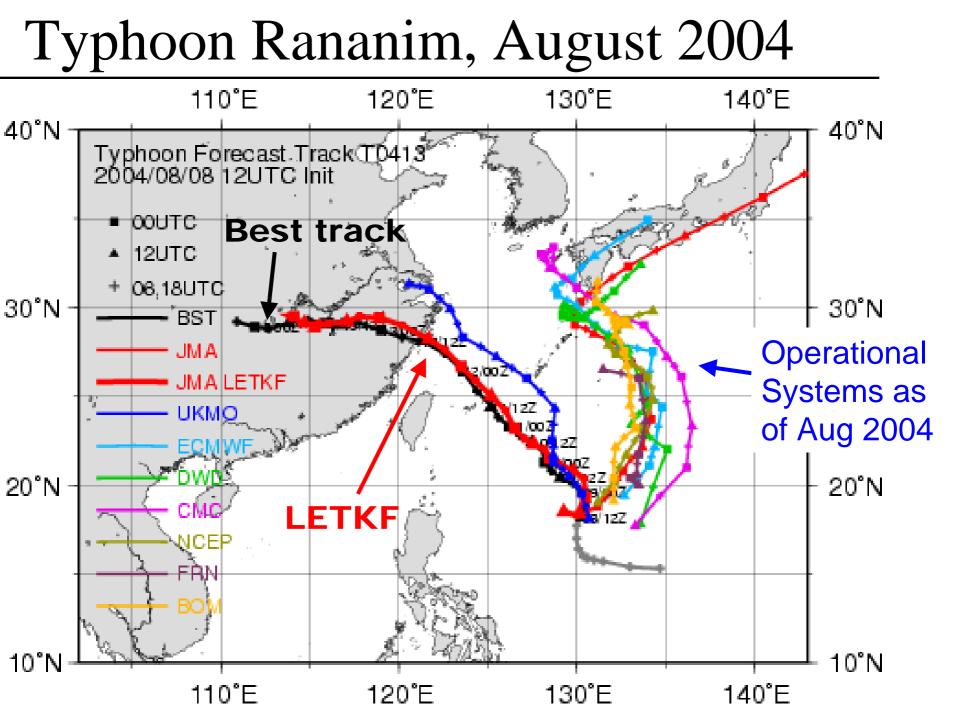


RMSE and bias against radiosondes Blue: w/o satellite radiances Red: w/ satellite radiances

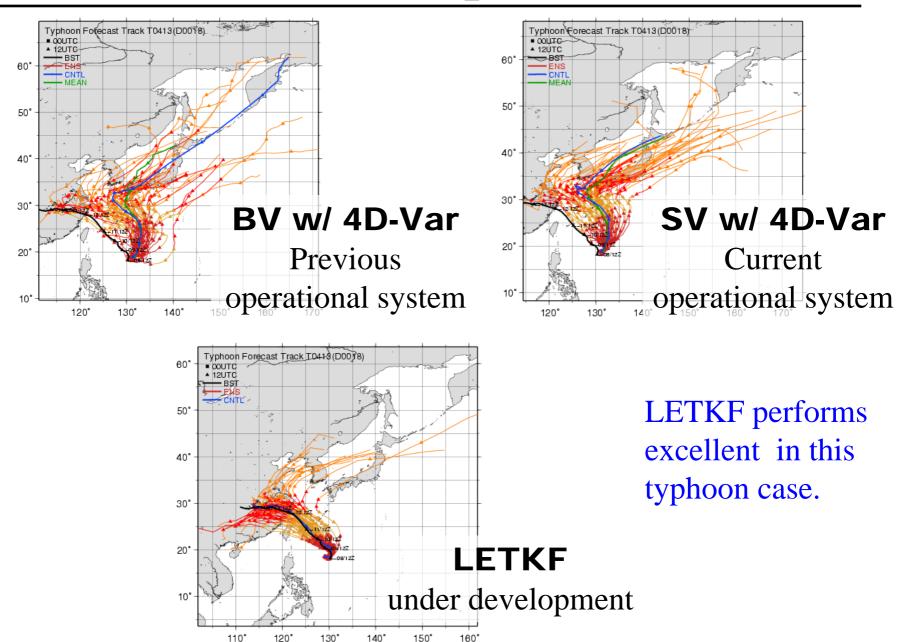
Reduced negative bias of Z and T

Reduced RMSE of Z in midupper troposphere (500-100hPa), especially in the SH and Tropics

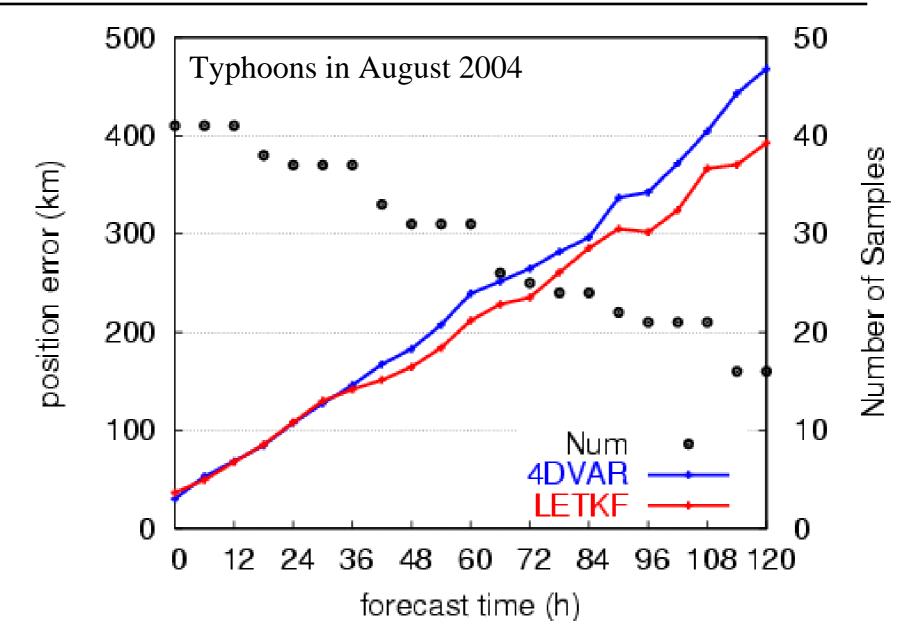
20 members



# TC track ensemble prediction



# Statistical typhoon track errors



### Improvement (%) relative to 4D-Var

	PseaSurf	T850	Z500	Wspd850	Wspd250
Global	-2.53	-2.04	-1.57	5.51	3.56
N. Hem.	-2.77	2.16	2.09	4.91	1.63
Tropics	7.05	4.90	4.95	14.92	11.81
S. Hem.	-3.06	-5.49	-2.68	2.62	1.91

#### August 2004

#### December 2005

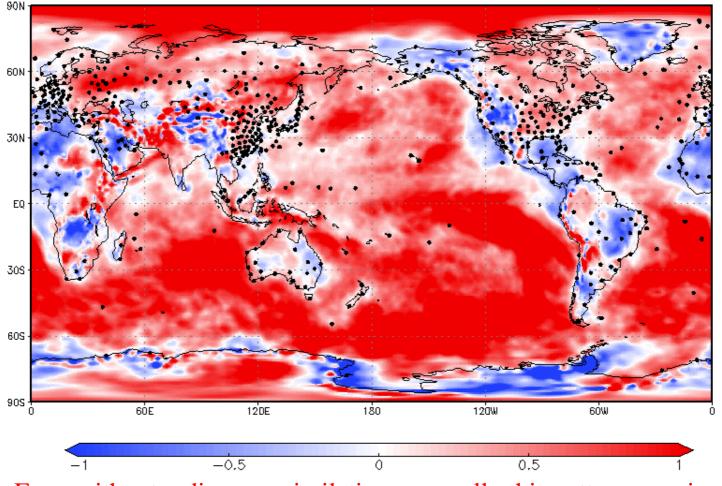
	PseaSurf	T850	Z500	Wspd850	Wspd250
Global	-3.39	-1.27	-2.60	4.91	2.69
N. Hem.	-5.60	-0.29	-4.46	1.16	0.83
Tropics	8.74	4.94	13.43	16.52	12.10
S. Hem.	-1.06	-4.98	-0.82	3.79	0.15

LETKF is advantageous in the summer hemisphere

## 850 hPa temperature bias

# 850 hPa Temperature bias of (LETKF – 4D-Var) 000HR T850 BIAS (ABC-4DV) Period: Aug

Period: August 2004



Even without radiance assimilation, generally this pattern remains. Namely, satellite radiances do not perfectly explain the positive bias.

# 話の流れのアイデア

- 4D-Varの背景誤差をいじると、良くなるらしい
   Flow dependentなBをEnKFから作ってあげると4D-Var はうれしいかも。という話
- JMAでのEnKF開発のこれまでを紹介
  - 4D-Varと比較しながらEnKFを改良してきた
  - 改善点の把握に4D-VarがBaselineとして役立つ
- EnKFのこれまでの開発で、4D-Varから学んできたこと
  - VarBCを参考にしたAdaptive BCの開発
     バイアスの容易な発見
- 現在のEnKFには、まだ弱点がある
  - 時空間積分量の観測に対するLocalizationなど
- EnKFが4D-Varよりも劣っている点を今後も改良していくという状況はしばらく続くだろう